

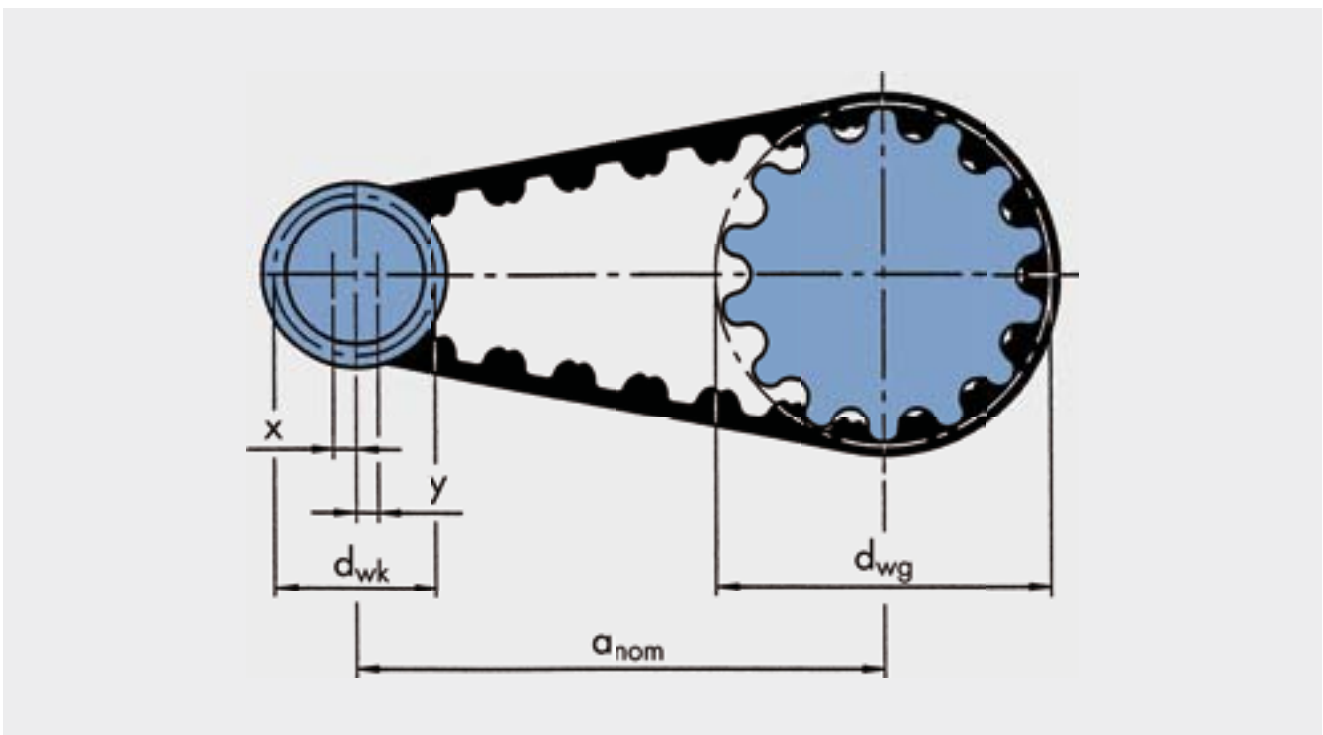
DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

EXPLANATION OF SYMBOLS



a	= Drive centre	[mm]	P	= Power to be transmitted by timing belt drive	[kW]
a_{nom}	= Drive centre distance with standard belt length	[mm]	P_B	= Design power	[kW]
c_0	= Basic load factor		P_N	= Rated power	[kW]
c_1	= Teeth in mesh factor		$P_{\ddot{U}}$	= Transmissible power for standard belt width $[P_N \cdot c_1 \cdot c_7]$	[kW]
c_2	= Overall load factor		S_a	= Minimum static shaft force when stationary	[N]
c_3	= Speed ratio correction factor		$S_{n\ zul}$	= Maximum allowed circumferential force	[N]
c_6	= Fatigue correction factor		S_{n3}	= Circumferential force to be effectively transmitted	[N]
c_7	= Belt length correction factor		S_n	= Effective circumferential force to be transmitted incl. actual centrifugal force	[N]
d_a	= Outside diameter of pulley	[mm]	t	= Tooth pitch	[mm]
d_w	= Pitch diameter of pulley	[mm]	v	= Belt speed	[m/s]
d_{wg}	= Pitch diameter of large pulley	[mm]	x	= Minimum adjustment of drive centre distance a_{nom} for tensioning timing belt	[mm]
d_{wk}	= Pitch diameter of small pulley	[mm]	y	= Minimum adjustment of drive centre distance a_{nom} for installation	[mm]
d_{w1}	= Pitch diameter of driving pulley	[mm]	z_e	= Number of teeth in mesh of small pulley	
d_{w2}	= Pitch diameter of driven pulley	[mm]	z_g	= Number of teeth on large pulley	
E_a	= Belt deflection for given span length	[mm]	z_k	= Number of teeth on small pulley	
F	= Force to create deflection	[N]	z_r	= Number of teeth on timing belt	
f	= Frequency	[Hz]	z_1	= Number of teeth on driving pulley	
i	= Speed ratio		z_2	= Number of teeth on driven pulley	
L	= Drive span length	[mm]			
L_{wSt}	= Standard pitch length of timing belt	[mm]			
L_{wth}	= Calculated pitch length of timing belt	[mm]			
n_1	= Speed of driving pulley	[min ⁻¹]			
n_2	= Speed of driven pulley	[min ⁻¹]			



DRIVE DESIGN

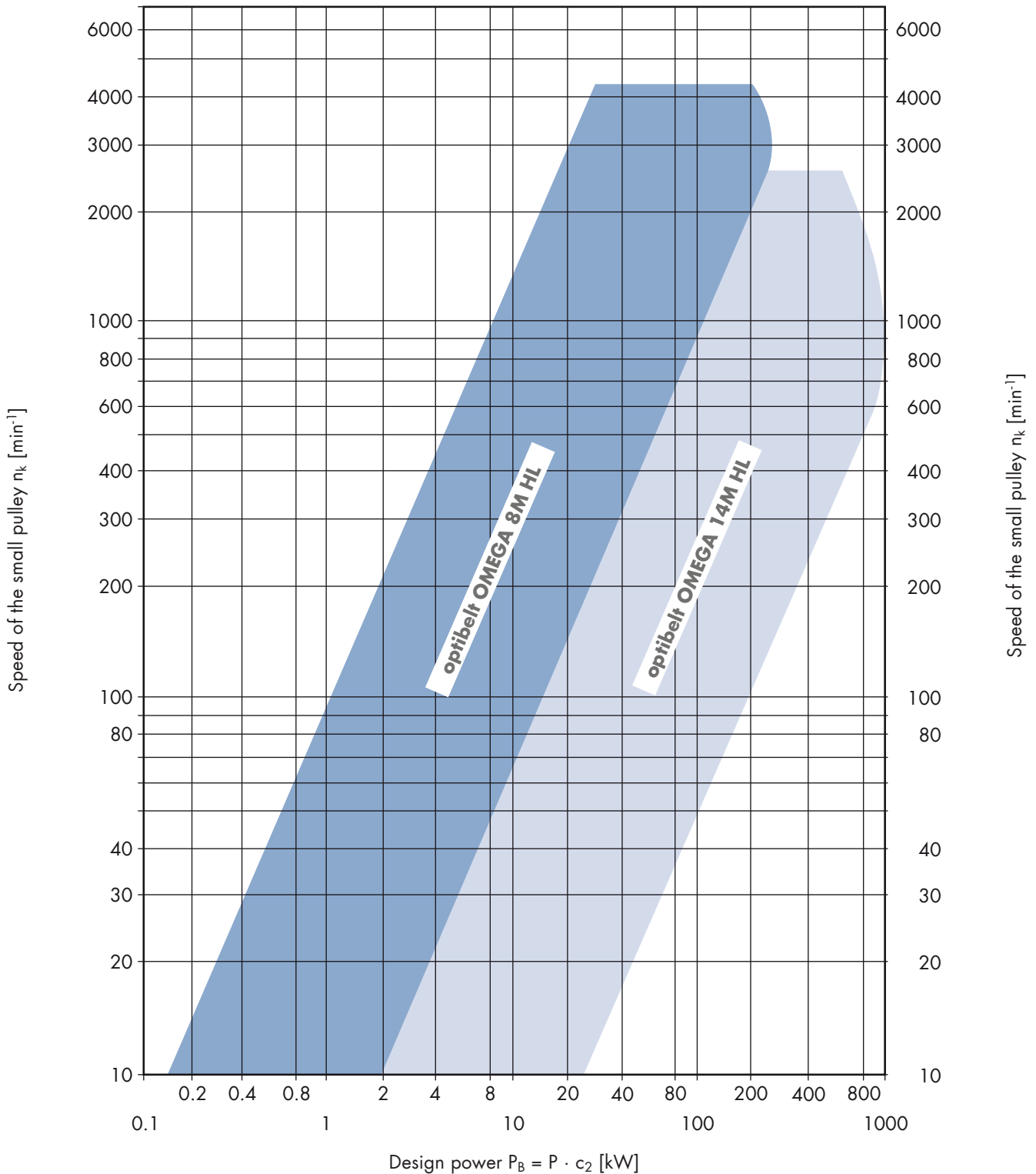
optibelt **OMEGA HL** TIMING BELTS

GUIDELINES FOR SELECTING THE TIMING BELT PROFILE



Diagram 1

Also see
optibelt CAP drive calculation
software at www.optibelt.com



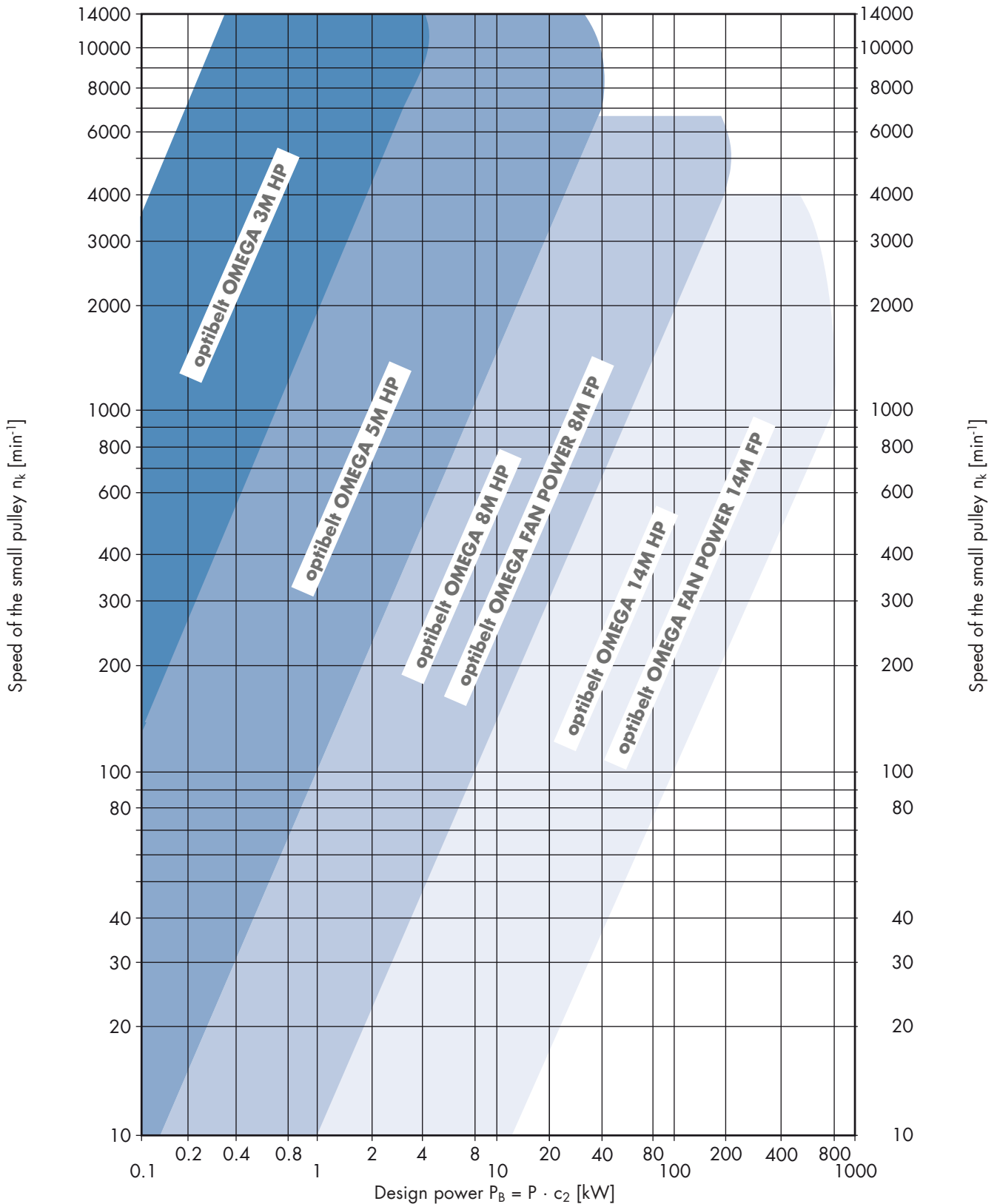
DRIVE DESIGN

optibelt OMEGA HP, optibelt OMEGA FAN POWER TIMING BELTS GUIDELINES FOR SELECTING THE TIMING BELT PROFILE



Diagram 2

Also see
optibelt CAP drive calculation
software at www.optibelt.com



DRIVE DESIGN

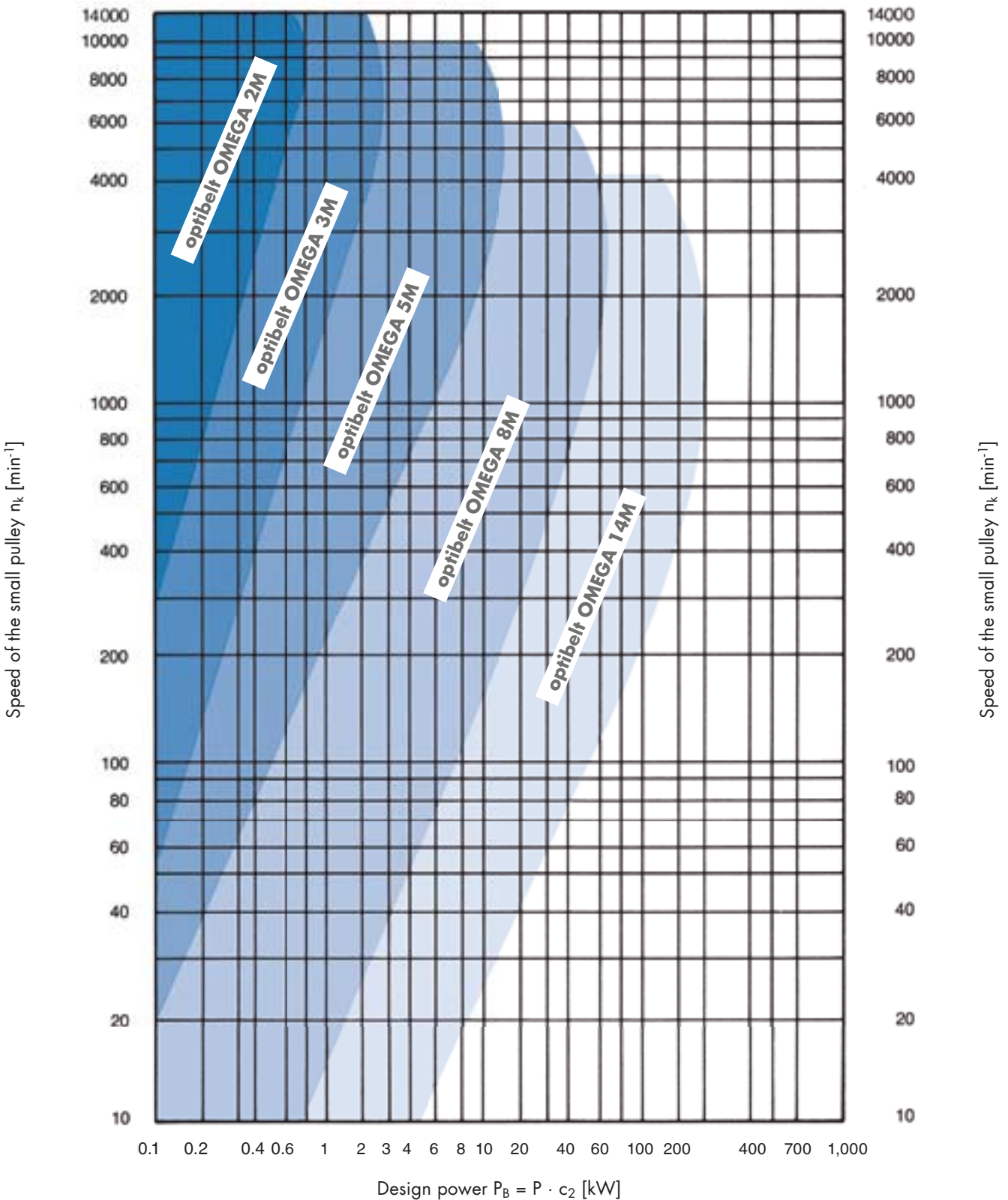
optibelt OMEGA TIMING BELTS

GUIDELINES FOR SELECTING THE TIMING BELT PROFILE



Diagram 3

Also see
optibelt CAP drive calculation
software at www.optibelt.com



DRIVE DESIGN

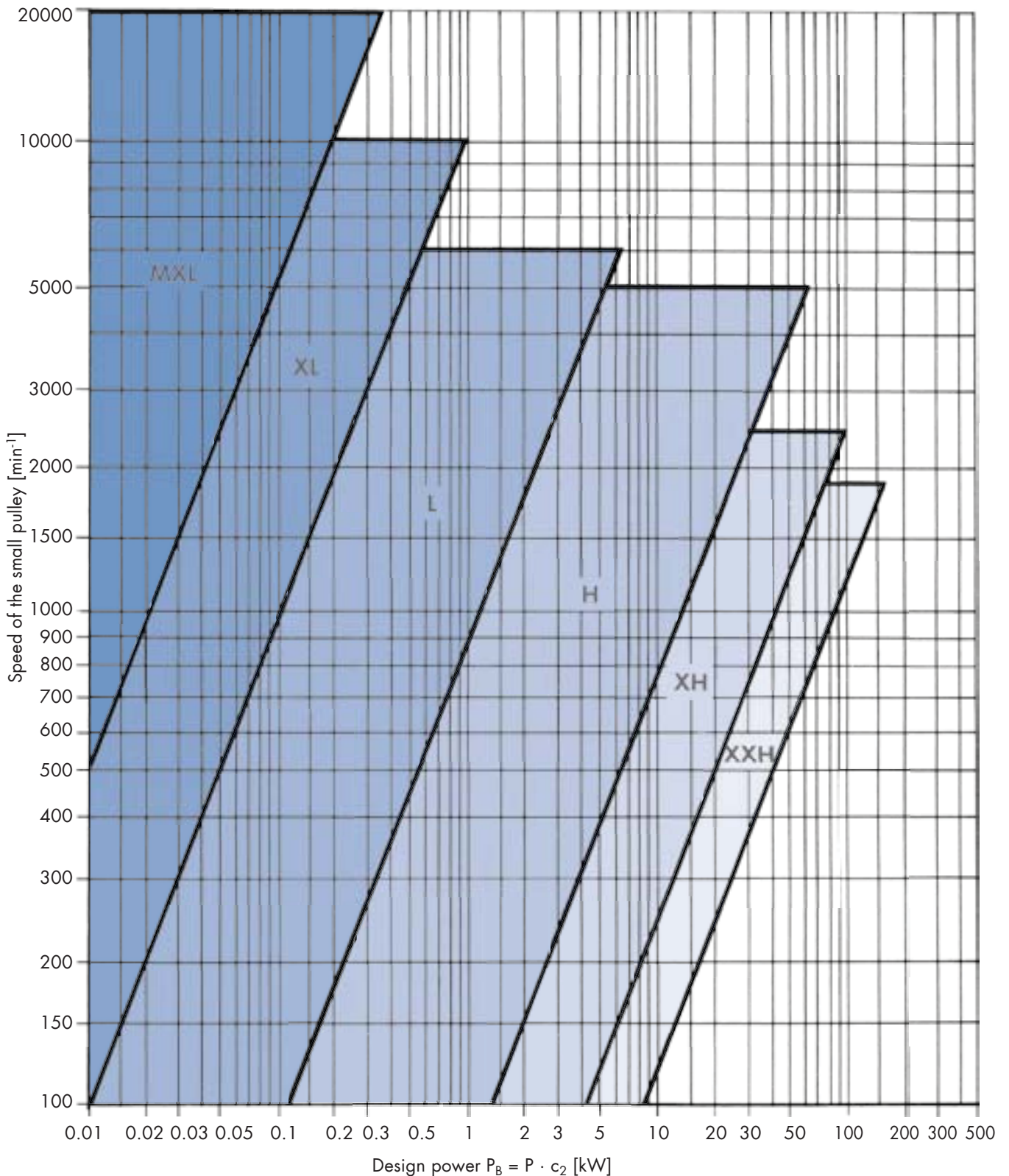
optibelt ZR TIMING BELTS

GUIDELINES FOR SELECTING THE TIMING BELT PROFILE



Diagram 4

Please also use software:
optibelt CAP drive calculation
and data optibelt CAD 2D / 3D
online at: www.optibelt.com



DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

LOAD FACTORS



Total load factor c_2

The total load factor c_2 is comprised of the basic load factor c_0 plus two further loads c_3 and c_6 .

$$c_2 = c_0 + c_3 + c_6$$

$$c_2 \geq M_A/M_N \quad \text{recommended for frequent starts and stops}$$

Basic load factor c_0

The basic load factor c_0 takes into account the daily operating time, the type of drive and the prime mover. As it is almost impossible to put all the possible combinations of prime mover / driven unit / environmental conditions in a shortened form which conforms to standards, the service factors shown here are given only as a guideline. The classification of the work machine is dependent on the respective present load type.

Table 5
Basic load factor c_0

Load type and examples for work machines	Load type and examples for drive machines			
	Continuous running		Non-continuous running	
	Electric motor Turbine running at high speed Reciprocating engine with higher quantity of cylinders		Hydraulic motor Turbine running at low speed Reciprocating engine with lower quantity of cylinders	
Basic load factor c_0 with daily operation times				
	up to 16 h	up to 16 h	up to 16 h	over 16 h
Light drives. shock-free with smooth running characteristics Measurement devices Film cameras Office machines Conveyor systems (light goods)	1.3	1.4	1.4	1.5
Medium drives. operation with smaller to medium intermittent shock strain Mixing machines Kitchen machines Printing shop machines Textile machines Packaging machines Conveyor systems (heavy goods)	1.6	1.7	1.8	1.9
Heavy drives. operation with medium to high intermittent shock strain Tool machines Wood processing machines Eccentric drives Conveyor systems (heavy goods)	1.8	1.9	2.0	2.1
Extremely heavy drives. operation with high constant shock strain Mills Calendars Extruders Piston pumps/compressors Lifting appliances	2.0	2.1	2.2	2.3

DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

ADDITIONAL FACTORS



Speed correction factor c_3

For speed increasing drives, a factor corresponding to the speed ratio is added to the basic load factor c_0 .

Table 6

Speed correction i	Speed correction factor c_3
1.00–0.80	0.0
0.79–0.57	0.1
0.56–0.40	0.2
0.39–0.28	0.3
0.27 and smaller	0.4

Table 7

Fatigue correction factor c_6

Operating conditions	Fatigue correction factor c_6
Use of tension or guide idlers	0.2
Operating time 16 to 24 hours	0.2
Only infrequent or occasional operation	-0.2

With frequent starts and stops or continual reversing operation, the selected total load factor c_2 should be higher than the ratio between starting torque and nominal torque. If there is a brake on the prime mover the same procedure should apply for the braking torque, if the brake is used frequently. For further questions, please contact the Optibelt Application Engineering Department.

Minimum adjustment of centre distance 'x' for tensioning of timing belts

$$x = 0.004 \cdot a_{nom}$$

Table 8

Minimum adjustment of centre distance 'y' for installation on timing belt pulleys without flanges

Axial distance [mm]	Shifting distance for the installation of the belt [mm]
Up to 1000	1.8
From 1000 to 1780	2.8
From 1780 to 2540	3.3
From 2540 to 3300	4.1
From 3300 to 4600	5.3

Table 9

Minimum adjustment of centre distance 'y' for installation on timing belt pulleys with flanges

Pitch [mm]	Flange on one timing pulley [mm]	Flange on both timing pulleys [mm]
2	6	12
3	8	14
5	14	19
8	22	33
14	36	58

Table 10

Belt length factor c_7

Profile 2M		Profile 8M	
Pitch length [mm]	c_7	Pitch length [mm]	c_7
≤ 190	0.8	≤ 600	0.8
> 190 ≤ 260	0.9	> 600 ≤ 880	0.9
> 260 ≤ 400	1.0	> 880 ≤ 1200	1.0
> 400 ≤ 600	1.1	> 1200 ≤ 1760	1.1
> 600	1.2	> 1760	1.2
Profile 3M		Profile 14M	
Pitch length [mm]	c_7	Pitch length [mm]	c_7
≤ 190	0.8	≤ 1190	0.80
> 190 ≤ 260	0.9	> 1190 ≤ 1610	0.90
> 260 ≤ 400	1.0	> 1610 ≤ 1890	0.95
> 400 ≤ 600	1.1	> 1890 ≤ 2450	1.00
> 600	1.2	> 2450 ≤ 3150	1.05
Profile 5M		> 3150	1.10
Pitch length [mm]	c_7		
≤ 440	0.8		
> 440 ≤ 555	0.9		
> 555 ≤ 800	1.0		
> 800 ≤ 1100	1.1		
> 1100	1.2		

Table 11

Teeth in mesh factor c_1

Number of meshing teeth	Teeth in mesh factor c_1
≥ 6	1.0
5	0.8
4	0.6
3	0.4
2	0.2

DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

FORMULAS AND CALCULATION EXAMPLES



Prime mover

Electric motor 50 Hz
Star delta start
 $P = 18.5 \text{ kW}$
 $n_1 = 2850 \text{ min}^{-1}$

Operating conditions

Daily operating time: 12 hours
Number of starts/stops: 2 per day
Environmental influences:
ambient room temperature,
no influence from oil, water or dust
Centre distance: 400 mm to 450 mm
Max. pulley diameter: 200 mm

Driven machine

Textile machine
 $P = 15 \text{ kW}$
 $n_2 = 1830 \text{ min}^{-1} \pm 1\%$
Type of load: constant

Also see
optibelt CAP drive calculation
software at www.optibelt.com

Formulae

Total load factor

$c_2 = c_0 + c_3 + c_6$
 c_0 from table 5, page 40
 c_3 from table 6, page 41
 c_6 from table 7, page 42

Design power

$$P_B = P \cdot c_2$$

Timing belt profile

from diagrams 1-4, pages 36-39

Speed ratio

$$i = \frac{n_1}{n_2} = \frac{z_2}{z_1} = \frac{d_{w2}}{d_{w1}}$$

Number of teeth of the pulleys

z_1, d_{w1} selected from standard range of timing belt pulleys page 75

$$z_2 = z_1 \cdot i$$

See to the minimum diameter requirement!

Check the rotary frequency

$$i = \frac{z_2}{z_1}$$

$$n_2 = \frac{n_1}{i}$$

Recommended centre distance

Recommendation:

$$a > 0.5 (d_{w1} + d_{w2}) + 15 \text{ mm}$$

$$a < 2.0 (d_{w1} + d_{w2})$$

Worked example

$$c_2 = 1.6 + 0 + 0 = \mathbf{1.6}$$

$$c_0 = 1.6$$

$$c_3 = 0$$

$$c_6 = 0$$

$$P_B = 18.5 \cdot 1.6 = \mathbf{29.6 \text{ kW}}$$

optibelt OMEGA HP

Type 8M

$$i = \frac{2850}{1830} = \mathbf{1.557}$$

$$z_1 = \mathbf{36}$$

$$d_{w1} = 91.67 \text{ mm}$$

$$z_2 = 36 \cdot 1.56 = 56.16$$

$$z_2 = \mathbf{56}$$

$$d_{w2} = 142.60 \text{ mm}$$

z_2 selected from standard range pulleys page 75

In compliance with requirement $z_1 \geq 22$ (minimum number of teeth for profile 8M)

$$i = \frac{56}{36} = 1.556$$

$$n_2 = \frac{2850}{1.556} = \mathbf{1832 \text{ min}^{-1}}$$

Requirement:
 $\mathbf{1830 \text{ min}^{-1} \pm 1\% \text{ met}}$

$$a > 0.5 (91.67 + 142.60) + 15 \text{ mm} = 132.14 \text{ mm}$$

$$a < 2.0 (91.67 + 142.60) = 468.54 \text{ mm}$$

$a = \mathbf{425 \text{ mm}}$ provisionally selected

DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

FORMULAS AND CALCULATION EXAMPLES



Formulas

Pitch length of the timing belt

$$L_{\text{with}} \approx 2a + \frac{\pi}{2} (d_{\text{wg}} + d_{\text{wk}}) + \frac{(d_{\text{wg}} - d_{\text{wk}})^2}{4a}$$

L_{wSt} see standard lengths,
see pages 10-11, 13, 16-19, 21-27, and 32-34

Centre distance from L_{wSt}

$$a_{\text{nom}} = K + \sqrt{K^2 - \frac{(d_{\text{wg}} - d_{\text{wk}})^2}{8}}$$

$$K = \frac{(L_{\text{wSt}})}{4} - \frac{\pi}{8} (d_{\text{wg}} + d_{\text{wk}})$$

Minimum adjustment for tensioning

$$x = 0.004 \cdot a_{\text{nom}}$$

Minimum adjustment for fitting belts

y = from table 9, page 41

Number of teeth in mesh on the small pulley

$$z_e = \frac{z_k}{6} \left(3 - \frac{d_{\text{wg}} - d_{\text{wk}}}{a_{\text{nom}}} \right)$$

Belt length factor

c_7 from table 10, page 41

Teeth in mesh factor

c_1 from table 11, page 41

Belt width above nominal power rating

Requirement: $P_{\text{Ü}} \geq P_{\text{B}}$

$P_{\text{Ü}}$ = transmissible nominal power of a standard belt width

$$P_{\text{Ü}} = P_{\text{N}} \cdot c_1 \cdot c_7$$

P_{N} value and, if required, width correction factor (which is to be multiplied by the P_{N} value) see pages 46 to 58

Worked example

$$L_{\text{with}} \approx 2 \cdot 425 + \frac{\pi}{2} (142.60 + 91.67) + \frac{(142.60 - 91.67)^2}{4 \cdot 425}$$

$$L_{\text{with}} \approx \mathbf{1219.33 \text{ mm}}$$

next standard belt length selected from page 18

$$L_{\text{wSt}} = \mathbf{1200 \text{ mm}}$$

$$a_{\text{nom}} = 208 + \sqrt{208^2 - \frac{(142.60 - 91.67)^2}{8}}$$

$$a_{\text{nom}} = \mathbf{415.22 \text{ mm}}$$

$$K = \frac{1200}{4} - \frac{\pi}{8} (142.60 + 91.67) = 208 \text{ mm}$$

$$x \geq \mathbf{1.66 \text{ mm}}$$

$$y = \mathbf{22 \text{ mm}}$$
 (with flanged pulley)

$$z_e = \frac{36}{6} \left(3 - \frac{142.60 - 91.67}{415} \right) = 17.26$$

$$z_e = \mathbf{17}$$

$$c_7 = \mathbf{1.0}$$

$$c_1 = \mathbf{1.0}$$

31.09 kW > 29.60 kW Requirement met!

$$P_{\text{Ü}} = 31.09 \cdot 1.0 \cdot 1.0 = \mathbf{31.09 \text{ kW}}$$

$$P_{\text{N}} \text{ for width of 30 mm} = 19.68 \cdot 1.58 = \mathbf{31.09 \text{ kW}}$$

Drive to be fitted with:

1 optibelt OMEGA HP timing belt	1200 8M HP 30
1 optibelt ZRS timing belt pulley	36 8M 30
1 optibelt ZRS timing belt pulley	56 8M 30

DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

BELT TENSION



Belt tension for optibelt OMEGA HP/optibelt OMEGA HL and optibelt OMEGA timing belts

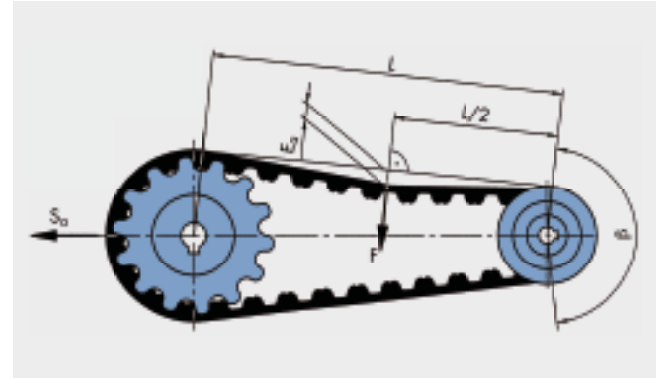
For proper power transmission and for achieving an acceptable belt service life, the correct belt tension is of the utmost importance.

Too low or too high belt tension will lead to the premature failure of the timing belts. Over tensioning often leads to bearing failure on the prime mover or the driven machine. Experience shows that unscientific belt tensioning methods, such as the "thumb pressure method", are not suitable for applying the optimum tension to the drive for maximum efficiency and drive/bearing life. It is therefore recommended that the correct static belt tension should be calculated for each drive. Due to their extremely low-stretch characteristics Optibelt timing belts do not require any further tensioning after correct installation, if properly used.

Symbol

F	= test force	[N]
S _α	= static shaft loading	[N]
S _{n3}	= circumferential force to be effectively transmitted	[N]
E _α	= belt deflection for given span length	[mm]
L	= span length	[mm]

Apply test force F in the centre of the span in a right angle to the belt top surface as shown in the illustration below; measure the deflection E_α, correct the tension if necessary.



1. Calculation of the test force F

$$F = \frac{S_{n3}}{20}$$

$$S_{n3} = \frac{P \cdot 1000}{v}$$

$$v = \frac{d_{wk} \cdot n_k}{19100}$$

$$F = \frac{1352}{20} = \mathbf{67.60 \text{ N}}$$

$$S_{n3} = \frac{18.5 \cdot 1000}{13.68}$$

$$v = \frac{91.67 \cdot 2850}{19100}$$

$$S_{n3} = 1352 \text{ N}$$

$$v = 13.68 \text{ m/s}$$

2. Calculation of the belt deflection E_α for the existing span length L

$$E_{\alpha} = \frac{L}{50}$$

$$L = \sqrt{\alpha_{nom}^2 - \left(\frac{d_{wg} - d_{wk}}{2}\right)^2}$$

$$E_{\alpha} = \frac{414.44}{50} = \mathbf{8.3 \text{ mm}}$$

$$L = \sqrt{415.22^2 - \left(\frac{142.60 - 91.67}{2}\right)^2} = 414.44 \text{ mm}$$

3. Calculation of the minimum static shaft loading

$$S_{\alpha} = S_{n3} \cdot 1.1$$

$$S_{\alpha} = 1352 \text{ N} \cdot 1.1 = \mathbf{1487.2 \text{ N}}$$

4. Calculation of the frequency for measuring the belt tension using the Optibelt frequency tension tester

$$f = \sqrt{\frac{T}{4 \cdot k \cdot L^2}}$$

$$T = 0.5 \cdot S_{\alpha}$$

k belt weight per metre from table 37, page 72

L span length per metre

$$f = \sqrt{\frac{743.6}{4 \cdot 0.174 \cdot 0.414^2}} = \mathbf{78.9 \text{ Hz}}$$

$$T = 0.5 \cdot 1487.2 \text{ N} = 743.6 \text{ N}$$

$$k = 0.174 \text{ kg/m}$$

$$L = 0.414 \text{ m}$$

DRIVE DESIGN

TIMING BELTS IN optibelt OMEGA PROFILE

optibelt CAP DRIVE CALCULATION



The drive is to be equipped with:

- optibelt OMEGA HP timing belt 1200 8M HP 30
- optibelt ZRS pulley 36-8M-30 (cylindrical bore)
- optibelt ZRS pulley 56-8M-30 (cylindrical bore)

Also use
the optibelt CAP drive calculation
Software available at www.optibelt.com

Prime mover Electric motor P = 18.5 kW
Driven machine Textile machine

<u>Timing belt data</u>		Variations/Information
Pitch	t: 8.000 mm	
Width	b: 30.00 mm	
Calculated pitch length	L _{wth} : 1200.00 mm	
Standard pitch length	L _w : 1200.00 mm	
Number of teeth	Z _r : 150	
Belt speed	v: 13.68 m/s	

<u>Timing belt pulley data</u>	Pulley 1 (driving)	Pulley 2 (driven)
Number of teeth	z: 36	56
Pitch diameter	d _w : 91.67 mm	142.60 mm
Pulley face width	b ₁ : 38.00 mm	38.00 mm
Speed	n: 2850.0 1/min	1832.1 1/min
Number of teeth in mesh	Z _e : 17	29
Torque	M: 104 Nm	162 Nm
Standard Design	6F	6WF
Number of flanged pulleys	2	2
Material	St	GG

<u>Nominal drive data</u>		Variations/Information
Design power	P_B: 29.60 kW	
Nominal power rating	P _Ü : 31.09 kW	
Effective service factor	c₂: 1.68	
Actual drive ratio	i: 1.56	0.0 %
Actual centre distance	a: 415.22 mm	-9.78 mm
Minimum adjustment of centre distance for belt installation	y: ≥ 22.00 mm	
Minimum adjustment of centre distance for belt tensioning	x: ≥ 1.66 mm	
Actual circumferential load	S _{n3} : 1353 N	
Static shaft load	S _a : 1488 N	
Static span tension	T: 744 N	
Span length	L: 414.50 mm	

Methods for setting belt tension

Belt deflection per span length optibelt TT 3	E _a : 8.29 mm with a load F 67.60 N
frequency tension tester	f: 78.88 1/s